Specialists Workshop on Advanced Human-Machine Systems Studies for Complex Energy Systems

Reliability/Availability evaluation of Heliotron by GO-FLOW

March 27, 2024, Uji, Kyoto, Japan

Takeshi Matsuoka (Utsunomiya University) mats@cc.utsunomiya-u.ac.jp

### **Contents of the presentation**

Heliotron J is a fusion research device located at the Institute of Advanced Energy, Kyoto University.

- Experiments by Heliotron J are continuously performed during half year and rest of the period is used for the maintenance of the system.
- For the successful operation of the system, availability of the water-cooling systems in the Heliotron J is essential matter.
- Reliability/availability of the cooling systems have been performed by the GO-FLOW methodology for possible maintenance schedules and methods.

# Heliotron J

- Heliotron J is a fusion research device, specifically a helical-axis heliotron designed to study plasma confinement.
- The first plasma has been produced in 1999. The purpose of the device is to demonstrate its improved helical confinement property in the helical-axis heliotron line.

 For the successful operation of the system, availability of the water-cooling systems in the Heliotron J is essential matter.

#### Major Components of composing Heliotron J system



# Main part of Heliotron J



T.Matsuoka (Utsunomiya University)

### Facility Operation Performance

- Since 1980, it has been in operation for 23 years (with a few years of inactivity), so the actual operating time is about 20 years.
- The experiment was conducted for approximately 6 months per year, 28 hours operation per week.
- The annual operating hours would be 28h/week x 6 months = 28x26 weeks = 728h/year.

➡Hence, the total operating time is 14,560 hours.
The elapsed time for the facility is 24x365x23 = 201,480 hours.



### Water-cooling systems in the Heliotron J



#### T.Matsuoka (Utsunomiya University)

# The following two diagrams can be created as a configuration diagram with the main equipment taken from the diagram on the previous page.





Operating conditions of the water cooling system

- > Inspection is performed once a year
- Water cooling system can be operated with one refrigeration unit.
- The cooling function can be maintained with three of the five cooling towers.



### Estimation of Equipment Failure Rates

- ✓ The total operating time is 14,560 hours and no failure has occurred in the 10 pumps installed during that time, the failure rate during pump operation is 1÷(10x14,560)=6.9x10<sup>-6</sup>/h or less.
- Since the total elapsed time is 201,480 hours, the standby failure rate during that time is obtained with the same considertion, 1 ÷ (10x201,480)=5x10<sup>-7</sup>/h or less.

Estimation of Equipment Failure Rates(2)

 There is an adjustment for water leakage from the pump bearings about once a year. The probability of failure will be about

 $1 \div (10x14,560) = 1.2x10^{-5}/h.$ 

 Two cooling towers experienced water leaks. The total elapsed time is 201,480 hours, so the standby failure rate during that time will be about,

 $2 \div (5x201, 480) = 2x10^{-6}/h.$ 

## *Estimation of Equipment Failure Rates(*<sup>3</sup>*)* ✓ Values adopted in other analysis cases

(1) Motor/Air operated valve	RSS
failure of open/close action 3.6x10 <sup>-3</sup> /D	1x10 <sup>-3</sup>
failure during usage 2.0x10 <sup>-7</sup> /hour	3x10 <sup>-5</sup>
failure during standby 2.0x10 <sup>-8</sup> /hour	
(2) Pump	
fails to start $2.7 \times 10^{-2}$ /D	1x10 <sup>-3</sup>
failure during operation 1.0x10 <sup>-6</sup> /hour	3x10 <sup>-6</sup>
(3) Turbine	
fails to start $2.7 \times 10^{-2}$ /D	
failure during operation 1.0x10 <sup>-6</sup> /hour	
(4) Turbine generator	

- fails to start 1x10<sup>-4</sup>/D
- failure during operation  $1.0 \mathrm{x} 10^{\text{-}6} / \mathrm{hour}$
- (5) Condensate water storage tank

failure during operation 2.8x10-8/hour

3x10<sup>-5</sup> 1x10<sup>-3</sup> 3x10<sup>-6</sup> T.Matsuoka (Utsunomiya University)

### ✓ Values adopted in other analysis cases (2)

Components	Capacity	Lifetime	Failure rate	
Solar panel	maximum 20kWh/day	30years	3.8E-6/h	Failure
Rechargeable battery	20kWh	10years	1.14E-5/h	Failure
Fuel cell	10kWh/day	60,000h	1.67E-5/h	Failure
Motor		50,000h	2E-5/h 1.1E-4/D	Failure to run Failure to start
Pump		50,000h	2E-5/h	Failure to run
H <sub>2</sub> tank			1.2E-7/h	Leak & Plug
O <sub>2</sub> flow			1E-8/h	Plug
DC-AC inverter			2.8E-7/h	Failure

### Failure rates set in this analysis

componentsPump,	Failure mode	Failure rates	remarks
Heliotron Main Part	Operating failure	2.0E-6/h	
same as above	Standby failure	2.0E-7/h	
Pump, Refrigerator, Cooling tower, Liquid resistor, Electric Generator, Discharge tube heater/cooler	Demand failure	1.0E-3/D	not take into account
same as above	Operating failure	1.0E-6/h	
same as above	Standby failure	1.0E-7/h	
valve	Operating failure	2.0E-7/h	
same as above	Standby failure	2.0E-8/h	
Tank and other components	Deterioration over time (aging)	2.8E-8/h	



T.Matsuoka (Utsunomiya University)

# The GO-FLOW Methodology

- GO-FLOW methodology is a success-oriented system analysis technique that is capable to evaluate reliability and/or availability of the systems with complex time-sequence and phased-mission problems.
- The GO-FLOW method can also deal with common cause failure (CCF) analysis with uncertainty. The modeling technique produces a chart which consists of signal lines and operators and represents the engineering function of the components/subsystems/system.

# The GO-FLOW Methodology(2)

- The GOFLOW operators' type, number, shape and functions are summarized in the following slides.
- The operators model function or failure of the physical equipment, logical gates, and signal transmissions.
- Specific probabilities (point estimates) of component operation or failure are given to operators as input data.

Туре	Shape	Main	Sub inputs	Output
Desc	Description Inputs		-	-
21		S(t)	_	$R(t) = S(t) \cdot P_g$
Two state	operator			
22	OR	$S_1(t), S_2(t)$	_	$R(t) = 1.0 - \prod_{i=1}^{n} [1.0 - S_i(t)]$
OR gate				<i>i</i> =1
23	NOT	S(t)	_	R(t) = 1.0 - S(t)
NOT gat	e.			
24	DIF	S(t)	-	R(t) = 1.0 - S(t') $R(t) = 0.0$
Difference	operator			21(q) - v.v
25		_	_	S(t) or $P(t)$
Signal g	enerator			
26		S(t)	P(t)	$R(t) = S(t) \cdot O(t),  O(t_1) = P_p$
Closed s operator	tate			$O(t) = O(t') + [1.0 - O(t')] \cdot P(t) \cdot P_g$
27		S(t)	P(t)	$R(t) = S(t) \cdot O(t),  O(t_1) = 1.0 - P_p$ $O(t) = O(t) \begin{bmatrix} 1 & 0 & P(t) & p \end{bmatrix}$
Open sta operator	te			$O(t) = O(t) \cdot \lfloor 1 \cdot 0 - F(t) \cdot F_g \rfloor$
	~			
28	DLY	S(t)	-	$R(t) = S(t-k); \ (t-k) > 0$ $R(t) = S(t_{0}); \ (t-k) \le 0$
Delay of	perator			
30	AND	$S_1(t), S_2(t)$ $\cdots S_n(t)$	-	$R(t) = \prod_{i=1}^{n} S_i(t)$
AND ga	te			<i>c</i> =⊾

T.Matsuoka (Utsunomiya University)

Туре	Shape	Main	Sub inpute	Output				
Desc	ription	inputs	Suo mpuis	Cuthur				
			$P_1(t_1), P_1(t_2) \cdots P_1(t_n); P_2(t_1), P_2(t_2) \cdots P_2(t_n); \cdots$					
35	$\bigcirc$	$S(t_1), S(t_2)$ $\cdots S(t_n)$	$R(t) = S(t) \left[ \frac{\mu}{2} + \frac{\lambda}{2} \exp\left\{ -(\lambda + \mu) \sum \sum P_{t}(t_{t}) \min\left[ 1.0, 1.0 \right] \right\} \right]$					
Aging w operator	ork		[ <i>A+µ</i> /	$i+\mu$ [ $i i i j \leq i$ [ $\mathcal{S}(t)$ ]]				
37		S(t)	$P_1(t_1), P_1(t_2) \cdots P_1(t_n)$ $P_2(t_1), P_2(t_2) \cdots P_2(t_n)$	$R(t) = S(t) \left[ \frac{\mu}{\lambda + \mu} + \frac{\lambda}{\lambda + \mu} \exp\left\{ -(\lambda + \mu) \sum_{i} \sum_{j} P_{i}(t_{i}) \right\} \right]$				
Aging operator	pen state							
38		S(t)	$P_1(t_1), P_1(t_2) \cdots P_1(t_n)$ $P_2(t_1), P_2(t_2) \cdots P_2(t_n)$	$R(t) = S(t) \left[ 1.0 - \frac{\mu}{2+\mu} - \frac{\lambda}{2+\mu} \exp\left\{ -(\lambda + \mu) \sum \sum P_i(t_i) \right\} \right]$				
Aging cl state ope	osed rator			ן איא איא <u>ן</u> זענא איזא ן				
39		S(t)	$P_1(t)$	$\begin{split} R(t) &= S(t) \cdot O(t),  O(t_1) = P_p \\ O(t) &= O(t') + \begin{bmatrix} 1.0 - O(t') \end{bmatrix} \cdot P_1(t) \cdot P_0 \end{split}$				
Open/Clo operator	ose action		$P_2(t)$	$O(t) = O(t') \cdot \left[1.0 - P_2(t) \cdot P_C\right]$				
40		S(t)	_	$R(t) = 1.0 ;  (t < t_i)$ $R(t) = S(t) ;  (t_i \le t \le t_j)$				
Phased n operator	nission			$R(t) = S(t_j) ;  (t_j \le t)$				

In this Figure,

S(t) = main input signal S at time point t,

P(t) =sub input signal at time point t,

R(t) =output signal at time point t,

O(t) = probability for value in open state at time point t,

t'= time point immediately before the time point t,

 $\underline{t_i}$ ,  $t_j$  = start time point and end time point of a specific phase,

k = number of time points delayed,

 $P_g = \text{probability for successful operation},$ 

 $P_p =$  probability for premature operation,

 $P_o =$  probability for valve successful open,

 $P_c =$  probability for valve successfully close,

 $\lambda = failure rate of a component,$ 

 $\mu =$  recovery rate of a component.

a University)

# Modeling to the GO-FLOW chart

- The first step of the analysis is to construct a GO-FLOW chart which consists of signal lines and operators to represent the engineering function of the components/subsystems/system composes the engineering system under consideration.
- GO-FLOW chart is constructed by using the Chart Editor as shown in the next slide.
- The GO-FLOW chart taking into account the system diagram, equipment operation, and maintenance and inspection.

### GO-FLOW chart editor





T.Matsuoka (Utsunomiya University)

# Conditions for inspection and repair

- There are so many components in the cooling systems, and it is very difficult to maintain all the components at every year.
- Important active components like pump, valve, motor are checked and repaired every year.
- Less important components as passive components like filter, pipes are checked once every two years or three years.
- Inspection and maintenance will not be conducted for other static equipment in some analysis case.
- The perfect maintenance; after the repair, components become as good as new.
- Less perfect maintenance is a graded recovery with considering different degree of restoration.

Time points defined in the analysis

Time point	meaning	month/day (weeks)	elapsed time	Operation time	Sandby time	Start of Operation	End of Operaion	Repair for operating Failure	Repair for standby Failure
1	First vear	1 (1/1)	0	0	0			I allule	I allule
2		· (1/1) <u>//(1</u> 3)	2160	0	2160				
2	start of operation	小/1(13週)	2160	0	2100	1			
 /		9/30(10))	6552	728	582/				
4 F	and of an aration	9/30(40週)	6552	720	5024 5024		1		
5 C		9/30(40週)	0002	120	5024		1	700	F040
6	repair	10/1(41)	0570	0	5848			-128	-5848
7	Seconf year	! (1/1)	8760	0	8032				
8		4/1(13週)	10920	0	10192				
9	start of operation	4/1(13週)	10920	0	10192	1			
10		9/30(40週)	15312	728	13856				
11	end of operation	9/30(40週)	15312	728	13856		1		
12	repair	10/1(41週)	15336	0	13880			-728	-8032
13	Third year	! (1/1)	17520	0	16064				
14		4/1(13週)	19680	0	18224				
15	start of operation	4/1(13週)	19680	0	18224	1		I	
16		9/30(40週)	24072	728	21888				
17	end of operation	9/30(40週)	24072	728	21888		1	1.1	
18	repair	10/1(41週)	24096	0	21912			-728	-8032
19	4th year	! (1/1)	26280	0	24096			Tra.	
20		4/1(13週)	28440	0	26256			<b>HI</b>	

### Time points defined in the analysis (Cont.)

Time point	meaning	month/day (weeks)	elapsed time	Operation time	Sandby time	Start of Operation	End of Operaion	Repair for operating Failure	Repair for standby Failure
21	start of operation	4/1(13週)	28440	0	26256	1			
22		9/30(40週)	32832	728	29920				
23	end of operation	9/30(40週)	32832	728	29920		1		
24	repair	10/1(41週)	32856	0	29944			-728	-8032
25	5th year	! (1/1)	35040	0	32128				+
26		4/1(13週)	37200	0	34288				
27	start of operation	4/1(13週)	37200	0	34288	1			
28		9/30(40週)	41592	728	37952				
29	end of operation	9/30(40週)	41592	728	37952		1		
30	repair	10/1(41週)	41616	0	37976			-728	-8032
31	6th year	! (1/1)	43800	0	40160				
32		4/1(13週)	45960	0	42320				
33	start of operation	4/1(13週)	45960	0	42320	1		L	THE CONTRACT
34		9/30(40週)	50352	728	45984				
35	end of operation	9/30(40週)	50352	728	45984		1	3	
36	repair	10/1(41週)	50376	0	46008			-728	-8032
37	End of 6th year	12・31(52週)	52560	0	48192			12	

### Analysis results (Base case)



Complete annual inspection and maintenance of the main body of the heliotron.

Pumps and valves were repaired for major failure modes foe once a year.

• No inspection and maintenance was performed on other static equipment.

T.Matsuoka (Utsunomiya University)

### (attention) Actual graph style



# Analysis conditions for other cases

- A) Careful inspection and repair will be performed for pumps, refrigerators, cooling towers, liquid resistors, electric generators, discharge tube heat coolers, and valves, covering also failure modes in standby mode. Inspection and maintenance will not be conducted for other static components.
- B) Major components will be divided into two groups, each of which will be carefully inspected and repaired every other two years.
- C) Major components will be divided into two groups, each of which will be inspected and repaired every other two years in response to operational failure modes.

T.Matsuoka (Utsunomiya University)

# Analysis results (2)



### Disscusions on the analysis results

- A relatively high level of reliability can be achieved by dividing major equipment into two groups, each of which is carefully inspected and repaired every other two years.
- Since the modeling and analysis system to this GO-FLOW chart has been established, analysis of other cases with different maintenance and inspection conditions can be easily performed.
- The failure rate set at this time can also be easily changed.
- Additions of components and system configuration changes that require consideration can be easily handled by modifying the existing GO-FLOW chart.

# Conclusions

- Reliability/availability analysis of the water cooling system, which plays an important role in the operation of Heliotron J, was performed using the GO-FLOW method.
- The results of the analysis provided useful knowledge.
- The GO-FLOW analysis is expected to be applied for further detailed analysis conditions.
  - Uncertainty analysis
  - Graded recovery

> Analysis cnditions for more realistic cases

T.Matsuoka (Utsunomiya University)